Nonparametric Estimation in Panel Data Models with Heterogeneity and Time–Varyingness

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Panel Data Analysis

1. Data Structure: Dependent Variable y_{it} and Independent Variable

 $\mathbf{x}_{it} = (X_{1,it}, X_{2,it}, \dots, X_{p,it})$ with $i = 1, 2, \dots, N$ and $t = 1, 2, \dots, T$.

- Aim: Accurately model and estimate the relation between y_{it} and x_{it} for all cross-sections i = 1, 2, ..., N and time-periods t = 1, 2, ..., T.
- 3. Major Benefit: Homogeneity (Blessing of Dimensionality).
- 4. Challenge: Heterogeneity (Curse of Dimensionality).

Bai (2009, Econometrica)

Common factor models are widely used to capture cross-sectional dependence in panel data sets:

$$y_{it} = \mathbf{x}_{it}^{\top} \boldsymbol{\beta} + e_{it}, \quad e_{it} = \boldsymbol{\lambda}_i^{\top} \mathbf{F}_t + \varepsilon_{it}$$
(1)

for i = 1, ..., N and t = 1, ..., T, where

- β is a *p*-dimensional unknown parameter;
- ► {**F**_{*t*}} are unknown *r*-dimensional common factors;
- $\{\lambda_i\}$ are corresponding factor loadings.

Advantages of factor models:

- heterogenous effects of common shocks;
- Appropriate flexibility.

Bai (2009, Econometrica)

 Bai (2009) proposes an iterative numerical method to approximate the minimizer of the least squares objective function:

$$SSR = \sum_{i=1}^{N} \sum_{t=1}^{T} \left(y_{it} - \mathbf{x}_{it}^{\top} \boldsymbol{\beta} - \boldsymbol{\lambda}_{i}^{\top} \mathbf{F}_{t} \right)^{2}$$
(2)

- Estimate β by least squares method;
- Estimate λ_i and \mathbf{F}_t by PCA method;
- Repeat until convergence.
- ► Extensions:
 - ► Ando and Bai (2014).
- ► Challenges:
 - ▶ Poor performance with endogenous factors (see Jiang et al., 2017).

Pesaran (2006, Econometrica)

▶ Pesaran (2006) proposes valid proxies for **F**_t in the following model:

$$\begin{pmatrix} y_{it} \\ \mathbf{x}_{it} \end{pmatrix} = \begin{pmatrix} \lambda_i^\top + \boldsymbol{\beta}_i^\top \boldsymbol{\gamma}_i^\top \\ \boldsymbol{\gamma}_i^\top \end{pmatrix} \mathbf{F}_t + \begin{pmatrix} \varepsilon_{it} + \boldsymbol{\beta}_i^\top \boldsymbol{\eta}_{it} \\ \boldsymbol{\eta}_{it} \end{pmatrix}, \quad (3)$$

where $\{\gamma_i\}$ are unknown factor loadings.

- Extensions: Chudik and Pesaran (2015).
- ► Challenges:
 - Rank condition $r \le p + 1$,
 - No estimators for \mathbf{F}_t , λ_i .

Time-varying panel data models

- Limitations of time-constant slope coefficients:
 - The risk of model misspecification;
 - ► The time-variation in parameters has been well recognized in many fields:
 - ► Silvapulle et al. (2017).
- Existing time-varying panel data models:
 - ► Li et al. (2011):

$$y_{it} = \mathbf{x}_{it}^{\top} \boldsymbol{\beta}_t + f_t + \alpha_i + \varepsilon_{it};$$
(4)

where $\boldsymbol{\beta}_t = \boldsymbol{\beta}(\tau_t)$ and $f_t = f(\tau_t)$ with $\tau_t = \frac{t}{T}$.

Heterogeneous panel data models

- Existing heterogeneous panel data models:
 - ► Pesaran (2006)'s random coefficient assumption:

$$\boldsymbol{\beta}_i = \boldsymbol{\beta} + \mathbf{u}_i. \tag{5}$$

Su et al. (2016)'s unknown group pattern:

$$\boldsymbol{\beta}_i = \sum_{k=1}^{K} \boldsymbol{\beta}^{(k)} \mathbf{1}\{i \in G_k\},\tag{6}$$

where *K* is known and fixed but G_k is unknown.

► Gao et al. (2019)'s complete heterogeneity:

$$y_{it} = \mathbf{x}_{it}^{\top} \boldsymbol{\beta}_i + f_{it} + \alpha_i + \varepsilon_{it}, \qquad (7)$$

where $f_{it} = f_i(\tau_t)$.

Proposed Model Our model

• We consider the following model:

$$y_{it} = \mathbf{x}_{it}^{\top} \boldsymbol{\beta}_{it} + \boldsymbol{\lambda}_i^{\top} \mathbf{F}_t + \varepsilon_{it}, \qquad (8)$$

where

- x_{it} and y_{it} are observable;
- $\beta_{it} = \beta_i(\tau_t)$ is an unknown deterministic function;
- \mathbf{x}_{it} can be correlated with $\{\lambda_i, \mathbf{F}_t\}$.

- 1. Generality of Model: Heterogeneous and Time-varying coefficients.
- 2. Unified Estimation Approach: observed, unobserved or partially observed factors.
- 3. Asymptotic Theory: reconcile computational elements (iteration steps) with statistical properties.
- 4. Empirical Application: relation between health care expenditure and income elasticity.

Proposed Estimation Approach

Recall the heterogeneous model:

$$y_{it} = \mathbf{x}_{it}^{\top} \boldsymbol{\beta}_i(\tau_t) + \boldsymbol{\lambda}_i^{\top} \mathbf{F}_t + \varepsilon_{it}.$$

The idea of iteration:

- With given \mathbf{F}_t , we can estimate $\boldsymbol{\beta}_i(\tau)$ and λ_i by a profile method.
- With $\beta_i(\tau)$ and λ_i , \mathbf{F}_t can be estimated by OLS method.

Estimation Procedure

- (1) Find an initial estimator $\widehat{\mathbf{F}}^{(0)} = (\widehat{\mathbf{F}}_1^{(0)}, \dots, \widehat{\mathbf{F}}_T^{(0)})^\top$.
- (2) With $\hat{\mathbf{F}}_{t}^{(n)}$ and by regarding λ_{i} as known, $\boldsymbol{\beta}_{i}(\tau)$ can be estimated by local linear method. For $\tau \in (0, 1)$

$$\min_{\mathbf{a}_{i}(\tau),\mathbf{b}_{i}(\tau)}\sum_{t=1}^{T}\left(y_{it}-\lambda_{i}^{\top}\widehat{\mathbf{F}}_{t}^{(n)}-\mathbf{x}_{it}^{\top}\left(\mathbf{a}_{i}(\tau)+\left(\frac{t-\tau T}{Th}\right)\mathbf{b}_{i}(\tau)\right)\right)^{2}K\left(\frac{t-\tau T}{Th}\right),\quad(9)$$

we have

$$\widehat{\boldsymbol{\beta}}_{i}^{(n+1)}(\tau,\boldsymbol{\lambda}_{i}) = \left[\mathbf{I}_{p},\mathbf{0}_{p}\right] \left[\mathbf{M}_{i}(\tau)^{\top}\mathbf{W}(\tau)\mathbf{M}_{i}(\tau)\right]^{-1}\mathbf{M}_{i}(\tau)^{\top}\mathbf{W}(\tau)\left[\mathbf{y}_{i}-\widehat{\mathbf{F}}^{(n)}\boldsymbol{\lambda}_{i}\right].$$
(10)

(3) With $\hat{\beta}_i(\tau, \lambda_i)$, we can estimate λ_i by the least squares method:

$$\min_{\boldsymbol{\lambda}_i} \sum_{t=1}^{T} \left(y_{it} - \mathbf{x}_{it}^{\top} \widehat{\boldsymbol{\beta}}_i^{(n+1)}(\tau, \boldsymbol{\lambda}_i) - \boldsymbol{\lambda}_i^{\top} \widehat{\mathbf{F}}_t^{(n)} \right)^2.$$
(11)

See notation

Estimation Procedure

We have

$$\widehat{\boldsymbol{\lambda}}_{i}^{(n+1)} = \left[\widehat{\mathbf{F}}^{(n)\top}(\mathbf{I} - \mathbf{S}_{i})^{\top}(\mathbf{I} - \mathbf{S}_{i})\widehat{\mathbf{F}}^{(n)}\right]^{-1}\widehat{\mathbf{F}}^{(n)\top}(\mathbf{I} - \mathbf{S}_{i})^{\top}(\mathbf{I} - \mathbf{S}_{i})\mathbf{y}_{i}, \quad (12)$$

where

$$\mathbf{S}_i = (\mathbf{s}_i(1/T)^\top \mathbf{x}_{i1}, \dots, \mathbf{s}_i(T/T)^\top \mathbf{x}_{iT})^\top,$$

with

$$\mathbf{s}_i(\tau) = [\mathbf{I}_p, \mathbf{0}_p] [\mathbf{M}_i(\tau)^\top \mathbf{W}(\tau) \mathbf{M}_i(\tau)]^{-1} \mathbf{M}_i(\tau)^\top \mathbf{W}(\tau).$$

After plugging $\widehat{\lambda}_i$ back into $\widehat{\beta}_i(\tau, \lambda_i)$, we have

$$\widehat{\boldsymbol{\beta}}_{i}^{(n+1)}(\tau) = [\mathbf{I}_{p}, \mathbf{0}_{p}] \left[\mathbf{M}_{i}(\tau)^{\top} \mathbf{W}(\tau) \mathbf{M}_{i}(\tau) \right]^{-1} \mathbf{M}_{i}(\tau)^{\top} \mathbf{W}(\tau) \left[\mathbf{y}_{i} - \widehat{\mathbf{F}}^{(n)} \widehat{\boldsymbol{\lambda}}_{i}^{(n+1)} \right]$$
(13)
for $i = 1, \dots, N$.

Estimation Procedure

(4) With
$$\widehat{\boldsymbol{\beta}}_{i}^{(n+1)}(\tau)$$
 and $\widehat{\boldsymbol{\lambda}}_{i}^{(n+1)}$, we can estimate \mathbf{F}_{t} by OLS method:

$$\widehat{\mathbf{F}}_{t}^{(n+1)} = \left(\widehat{\boldsymbol{\Lambda}}^{(n+1)\top}\widehat{\boldsymbol{\Lambda}}^{(n+1)}\right)^{-1}\widehat{\boldsymbol{\Lambda}}^{(n+1)\top}\mathbf{R}_{1,t}^{(n+1)}$$
where $\mathbf{R}_{1,t}^{(n+1)} = \left(y_{1t} - \mathbf{x}_{1t}^{\top}\widehat{\boldsymbol{\beta}}_{1}^{(n+1)}(\tau_{t}), \dots, y_{Nt} - \mathbf{x}_{Nt}^{\top}\widehat{\boldsymbol{\beta}}_{N}^{(n+1)}(\tau_{t})\right)^{\top}$.
(5) Benerat Comp. 2.4 until answer as

(5) Repeat Steps 2-4 until convergence.

Assumption 1

(i-v) Regularity assumptions on weak serial and cross-sectional dependence and kernel estimation.

(vi) Let $\mathbf{R}_{F}^{(n)} = \widehat{\mathbf{F}}^{(n)} - \mathbf{F}^{0}$. For the initial estimator $\widehat{\mathbf{F}}^{(0)}$, suppose that

$$T^{-1/2} \| \mathbf{R}_{F}^{(0)} \| = O_{P} \left(\delta_{F,0} \right) \text{ and } (Th)^{-1/2} \| \mathbf{W}(\tau)^{\top} \mathbf{R}_{F}^{(0)} \| = O_{P} \left(\delta_{F,0} \right),$$

where $\delta_{F,0}$ satisfies that $NTh^4 \delta_{F,0}^2 \to 0$, $\delta_{F,0}^2/h \to 0$ and $\max\{N, T\}\delta_{F,0}^4/h \to 0$, as $N, T \to \infty$.

Assumption 2

 (i-iv) Regularity assumptions on positive definiteness of asymptotic covariance matrices.

Theorem 2.1 (Consistency) Under Assumption 1, as $N, T \to \infty$ simultaneously, (1) $N^{-1/2} \|\widehat{\mathbf{A}}^{(n)} - \mathbf{A}\| = O_p (\max \{\delta_{F,0}, \delta_{NT}\});$ (2) $T^{-1/2} \|\widehat{\mathbf{F}}^{(n)} - \mathbf{F}\| = O_p (\max \{\delta_{F,0}, \delta_{NT}\}),$ where $\delta_{NT} = \min\{\sqrt{N}, \sqrt{T}\}^{-1}$.

Assume that

$$\mathbf{x}_{it} = \mathbf{g}_i(\tau_t) + \mathbf{v}_{it}.\tag{14}$$

Notations:

$$\begin{split} \boldsymbol{\Sigma}_{v,i} &= E\left[\mathbf{v}_{i1}\mathbf{v}_{i1}^{\top}\right], \quad \boldsymbol{\Sigma}_{F} = E\left[\mathbf{F}_{1}^{0}\mathbf{F}_{1}^{0\top}\right], \quad \boldsymbol{\Sigma}_{v,F,i} = E\left[\mathbf{v}_{it}\mathbf{F}_{t}^{0\top}\right], \quad \boldsymbol{\Sigma}_{v,\lambda,i} = E\left[\mathbf{v}_{it}\lambda_{i}^{0\top}\right], \\ \boldsymbol{\Sigma}_{X,i}(\tau) &= \mathbf{g}_{i}(\tau)\mathbf{g}_{i}^{\top}(\tau) + \boldsymbol{\Sigma}_{v,i}, \quad \boldsymbol{\Omega}_{F,i} = \boldsymbol{\Sigma}_{F} - \boldsymbol{\Sigma}_{v,F,i}^{\top} \int_{0}^{1} \boldsymbol{\Sigma}_{X,i}^{-1}(\tau)d\tau\boldsymbol{\Sigma}_{v,F,i}, \\ \sigma_{ij,ts} &= E[\varepsilon_{it}\varepsilon_{js}], \quad \mathbf{z}_{it} = \mathbf{F}_{t}^{0} - \boldsymbol{\Sigma}_{v,F,i}^{\top}\boldsymbol{\Sigma}_{X,i}^{-1}(\tau_{t})\mathbf{x}_{it}, \quad \boldsymbol{\Sigma}_{\lambda} = \lim_{N \to \infty} N^{-1}\sum_{i=1}^{N} \lambda_{i}^{0}\lambda_{i}^{0\top}, \\ \boldsymbol{\Delta}_{F,i} &= \boldsymbol{\Sigma}_{v,F,i}\boldsymbol{\Omega}_{F,i}^{-1}\boldsymbol{\Sigma}_{v,F,i}^{\top}, \quad \lambda_{i}^{\dagger}(\tau) = \boldsymbol{\Sigma}_{X,i}^{-1}(\tau)\left(\boldsymbol{\Sigma}_{v,\lambda,i}(\tau) + \mathbf{g}_{i}(\tau)\lambda_{i}^{0\top}\right), \\ \boldsymbol{\Omega}_{1}(t,s) &= N^{-1}\sum_{i=1}^{N} E\left[\lambda_{i}^{0}\lambda_{i}^{0\top}\mathbf{x}_{it}^{\top}\boldsymbol{\Sigma}_{X,i}^{-1}(\tau_{t})\mathbf{x}_{is}\right], \quad \boldsymbol{\Omega}_{2}(t,s) = N^{-1}\sum_{i=1}^{N} E\left[\lambda_{i}^{0}\lambda_{i}^{0\top}\mathbf{z}_{it}^{\top}\boldsymbol{\Omega}_{F,i}^{-1}\mathbf{z}_{is}\right], \\ \boldsymbol{\Omega}_{3}(t,s) &= \boldsymbol{\Sigma}_{\lambda}^{-1}(h^{-1}K_{s,0}(\tau_{t})\boldsymbol{\Omega}_{1}(t,s) + \boldsymbol{\Omega}_{2}(t,s)), \end{split}$$

Theorem 2.2 (CLT, $n \ge 2$) Let Assumptions 1 and 2 hold. Then, as $N, T \rightarrow \infty$ simultaneously,

(1) if $N/T \rightarrow c_1 < \infty$, for any given *t*, we have

$$\sqrt{N}\left(\widehat{\mathbf{F}}_{t}^{(n)}-\mathbf{F}_{t}^{0}-\mathbf{b}_{F,t}^{\dagger(n)}\right)\stackrel{D}{\longrightarrow}\mathcal{N}(\sqrt{c_{1}}\mathbf{d}_{F,t},\boldsymbol{\Sigma}_{F,t}),$$

where $\Sigma_{F,t} = \Sigma_{\lambda}^{-1} \Sigma_{F,t}^{0} \Sigma_{\lambda}^{-1}$,

$$\mathbf{b}_{F,t}^{\dagger(n)} = T^{-n} \sum_{s_1, s_2, \dots, s_n = 1}^T \mathbf{\Omega}_3(t, s_1) \prod_{j=1}^{n-1} \mathbf{\Omega}_3(s_j, s_{j+1})) \mathbf{R}_{F, s_n}^{(0)},$$

$$\mathbf{d}_{F,t} = \lim_{N, T \to \infty} 1/(N\sqrt{T}) \mathbf{\Sigma}_{\lambda}^{-1} \sum_{i=1}^N \sum_{s=1}^T \mathbf{\Omega}_{F,i}^{-1} \mathbf{\Sigma}_{v,F,i}^\top \mathbf{\Sigma}_{X,i}^{-1}(\tau_s) \mathbf{g}_i(\tau_s) \sigma_{ii,ts}.$$

Theorem 2.2 (CLT, $n \ge 2$) Let Assumptions 1 and 2 hold. Then, and as $N, T \rightarrow \infty$ simultaneously,

(2) if $T/N \rightarrow c_2 < \infty$, for any given *i*, we have

$$\sqrt{T}\left(\widehat{\boldsymbol{\lambda}}_{i}^{(n)}-\boldsymbol{\lambda}_{i}^{0}-\mathbf{b}_{\lambda,i}^{\dagger(n)}\right)\xrightarrow{D}\mathcal{N}(\sqrt{c_{2}}\mathbf{d}_{\lambda,i},\boldsymbol{\Sigma}_{\lambda,i}),$$

where $\Sigma_{\lambda,i} = \mathbf{\Omega}_{F,i}^{-1} \Sigma_{\lambda,i}^{0} \mathbf{\Omega}_{F,i}^{-1}$,

$$\mathbf{b}_{\lambda,i}^{\dagger(n)} = T^{-1} \mathbf{\Omega}_{F,i}^{-1} \mathbf{\Sigma}_{v,F,i}^{\top} \sum_{t=1}^{T} \lambda_{i}^{\dagger}(\tau_{t}) \mathbf{b}_{F,t}^{\dagger(n-1)},$$
$$\mathbf{d}_{\lambda,i}^{*} = 1/\sqrt{N} \mathbf{\Omega}_{F,i}^{-1} \mathbf{\Sigma}_{\lambda}^{-1} \boldsymbol{\mu}_{\lambda} \sum_{j=1}^{N} \sigma_{ij,11}.$$

Theorem 2.2 (CLT, $n \ge 2$) Let Assumptions 1 and 2 hold. Then, as $N, T \rightarrow \infty$ simultaneously,

(3) for any given (i, τ) , we have

$$\begin{split} \sqrt{Th} \left(\widehat{\boldsymbol{\beta}}_{i}^{(n)}(\tau) - \boldsymbol{\beta}_{i}(\tau) - \mathbf{a}_{i}(\tau)h^{2} - \mathbf{b}_{\beta,i}^{\dagger(n)}(\tau) \right) & \stackrel{D}{\longrightarrow} \mathcal{N}(0_{p}, \boldsymbol{\Sigma}_{\beta,i}(\tau)), \\ \text{where } \mathbf{a}_{i}(\tau) = \frac{\mu_{2}}{2} \boldsymbol{\beta}_{i}^{\prime\prime}(\tau)(1 + o(1)), \\ \boldsymbol{\Sigma}_{\beta,i}(\tau) = \boldsymbol{\Sigma}_{X,i}^{-1}(\tau)\boldsymbol{\Sigma}_{\beta,i}^{0}(\tau)\boldsymbol{\Sigma}_{X,i}^{-1}(\tau), \\ \mu_{2} = \int u^{2}K(u)du, \text{ and} \end{split}$$

$$\mathbf{b}_{\beta,i}^{\dagger(n)}(\tau) = -T^{-1} \mathbf{\Sigma}_{X,i}^{-1}(\tau) \sum_{t=1}^{I} \left(h^{-1} K_{t,0}(\tau) \mathbf{\Sigma}_{X,i}(\tau) + \mathbf{\Delta}_{F,i} \right) \lambda_{i}^{\dagger}(\tau_{t}) \mathbf{b}_{F,t}^{\dagger(n-1)}.$$

Corollary 2.1 (CLT, $n \ge 2$) Let Assumptions 1 and 2 hold. If ε_{it} is both serially and cross-sectionally uncorrelated, as $N, T \to \infty$ simultaneously,

(1)
$$\sqrt{N}\left(\widehat{\mathbf{F}}_{t}^{(n)} - \mathbf{F}_{t}^{0} - \mathbf{b}_{F,t}^{\dagger(n)}\right) \xrightarrow{D} \mathcal{N}(0_{r}, \mathbf{\Sigma}_{F,t});$$

(2) $\sqrt{T}\left(\widehat{\lambda}_{i}^{(n)} - \lambda_{i}^{0} - \mathbf{b}_{\lambda,i}^{\dagger(n)}\right) \xrightarrow{D} \mathcal{N}(0_{r}, \mathbf{\Sigma}_{\lambda,i}^{*});$
(3) $\sqrt{Th}\left(\widehat{\boldsymbol{\beta}}_{i}^{(n)}(\tau) - \boldsymbol{\beta}_{i}(\tau) - \mathbf{a}_{i}(\tau)h^{2} - \mathbf{b}_{\beta,i}^{\dagger(n)}(\tau)\right) \xrightarrow{D} \mathcal{N}(0_{p}, \mathbf{\Sigma}_{\beta,i}^{*}(\tau));$
where $\mathbf{\Sigma}_{\lambda,i}^{*} = \mathbf{\Omega}_{F,i}^{-1}\sigma_{\epsilon}^{2}$ and $\mathbf{\Sigma}_{\beta,i}^{*}(\tau) = v_{0}\mathbf{\Sigma}_{X,i}^{-1}(\tau)\sigma_{\epsilon}^{2}.$

Define

$$\kappa = \lim_{N,T\to\infty} (NT)^{-1} \sum_{s=1}^{T} \sum_{i=1}^{N} \mathbf{g}_i^{\top}(\tau_t) \boldsymbol{\Sigma}_{X,i}^{-1}(\tau_t) \left(\boldsymbol{\Sigma}_{v,F,i} \boldsymbol{\Omega}_{F,i}^{-1} \boldsymbol{\Sigma}_{v,F,i}^{-1} \boldsymbol{\Sigma}_{X,i}^{-1}(\tau_s) \mathbf{g}_i(\tau_s) + \mathbf{g}_i(\tau_t) \right) \in [0,1).$$

Theorem 2.3 (CLT, $n \rightarrow \infty$ **)** Let Assumptions 1-3 hold. Suppose

$$\max\left\{\sqrt{N},\sqrt{T}\right\}\kappa^{n-2}\delta_{F,0}\to 0.$$

We have

(1) If, in addition, $N/T \rightarrow c_1 < \infty$,

$$\sqrt{N}\left(\widehat{\mathbf{F}}_{t}^{(n)}-\mathbf{F}_{t}^{0}\right)\overset{D}{\longrightarrow}\mathcal{N}(\sqrt{c_{1}}\mathbf{d}_{F,t},\boldsymbol{\Sigma}_{F,t}),$$

(2) If, in addition, $T/N \rightarrow c_2 < \infty$,

$$\sqrt{T}\left(\widehat{\boldsymbol{\lambda}}_{i}^{(n)}-\boldsymbol{\lambda}_{i}^{0}\right) \xrightarrow{D} \mathcal{N}(\sqrt{c_{2}}\mathbf{d}_{\lambda,i},\boldsymbol{\Sigma}_{\lambda,i}),$$

(3) For any given $\tau \in (0, 1)$,

$$\sqrt{Th}\left(\widehat{\boldsymbol{\beta}}_{i}^{(n)}(\tau)-\boldsymbol{\beta}_{i}(\tau)-\mathbf{a}_{i}(\tau)h^{2}\right)\xrightarrow{D}\mathcal{N}(0_{p},\boldsymbol{\Sigma}_{\boldsymbol{\beta},i}(\tau))$$

See Assumptions

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Consider the following mean-group estimator (MGE)

$$\widehat{\boldsymbol{\beta}}_w^{(n)}(au) = \sum_{i=1}^N w_{N,i} \widehat{\boldsymbol{\beta}}_i^{(n)}(au),$$

where $w_{N,i} \ge 0$ and $\sum_{i=1}^{N} w_{N,i} = 1$.

Theorem 2.4 (CLT, MGE) Let Assumptions 1-4 hold. Suppose

$$\sqrt{\gamma_{N,w} Th} \kappa^{n-2} \delta_{F,0} \to 0.$$

We have

$$\sqrt{\gamma_{N,w}Th}\left(\widehat{\boldsymbol{\beta}}_{w}^{(n)}(\tau) - \boldsymbol{\beta}_{w}(\tau) - \mathbf{a}_{w}(\tau)h^{2}\right) \xrightarrow{D} \mathcal{N}(0_{p}, \boldsymbol{\Sigma}_{\boldsymbol{\beta}, w}),$$
(15)

where

•
$$\gamma_{N,w} = \left(\sum_{i=1}^{N} w_{N,i}^2\right)^{-1}$$
,
• $\mathbf{a}_w(\tau) = \frac{\mu_2}{2} \sum_{i=1}^{N} w_{N,i} \boldsymbol{\beta}_i''(\tau) (1 + o_P(1)), \, \boldsymbol{\beta}_w(\tau) = \sum_{i=1}^{N} w_{N,i} \boldsymbol{\beta}_i(\tau).$

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Exogenous factor models

Step 1. First, by the local linear method:

$$\widehat{\boldsymbol{\beta}}_{i}^{(0)}(\tau) = \left[\mathbf{I}_{p}, \mathbf{0}_{p}\right] \left(\mathbf{M}_{i}^{\top}(\tau)\mathbf{W}(\tau)\mathbf{M}_{i}(\tau)\right)^{-1} \mathbf{M}_{i}^{\top}(\tau)\mathbf{W}(\tau)\mathbf{y}_{i}.$$
(16)

Step 2. Second, by PCA:

$$\frac{1}{NT}\sum_{i=1}^{N} \mathbf{R}_{2,i} \mathbf{\bar{F}}^{(0)} = \widehat{\mathbf{F}}^{(0)} \mathbf{V}_{NT,1},$$
(17)

where $\mathbf{R}_{2,i} = (R_{i1}(\widehat{\boldsymbol{\beta}}_i^{(0)}(\tau_1)), \cdots, R_{iT}(\widehat{\boldsymbol{\beta}}_i^{(0)}(\tau_T)))^{\top}$ with $R_{it}(\boldsymbol{\beta}) = y_{it} - \mathbf{x}_{it}^{\top}\boldsymbol{\beta}$, and $\mathbf{V}_{NT,1}$ is an $r \times r$ diagonal matrix with diagonal elements being the first r largest eigenvalues of the matrix $(NT)^{-1} \sum_{i=1}^{N} \mathbf{R}_{2,i} \mathbf{R}_{2,i}^{\top}$.

Exogenous factor models

Corollary 3.1 (CLT, exogenous factor case) Let Assumptions 1.(i-v), 2-3, 5 hold. Suppose

$$\max\left\{\sqrt{\frac{N}{Th}},\sqrt{\frac{T}{N}}\right\}\kappa^{n-2}\to 0.$$

We have Theorem 2.3.(1-3) holds.

Endogenous factor models

Assume that

$$\mathbf{x}_{it} = \mathbf{g}_i(\tau_t) + \mathbf{v}_{it}, \quad \mathbf{v}_{it} = \boldsymbol{\gamma}_i^{0\top} \mathbf{F}_t^0 + \boldsymbol{\eta}_{it}.$$
(18)

Step 1. First, by the local linear method:

$$\widehat{g}_{i}^{(w)}(\tau) = [1,0] \left(\mathbf{M}_{T}^{\top}(\tau) \mathbf{W}(\tau) \mathbf{M}_{T}(\tau) \right)^{-1} \mathbf{M}_{T}^{\top}(\tau) \mathbf{W}(\tau) \widetilde{\mathbf{x}}_{i}^{(w)}$$
(19)

where $\widehat{g}_i^{(w)}(\tau)$ is the *w*-th element of $\widehat{\mathbf{g}}_i(\tau)$, $\widetilde{\mathbf{x}}_i^{(w)} = \left(x_{i1}^{(w)}, \cdots, x_{iT}^{(w)}\right)^\top$ and $x_{it}^{(w)}$ is the *w*-th element of \mathbf{x}_{it} , for $w = 1, 2, \dots, p$.

Step 2. Second, by PCA:

$$\left(\frac{1}{NTp}\sum_{w=1}^{p}\widetilde{\mathbf{R}}_{g}^{(w)}\widetilde{\mathbf{R}}_{g}^{(w)\top}\right)\widehat{\mathbf{F}}^{(0)}=\widehat{\mathbf{F}}^{(0)}\mathbf{V}_{NT,2}$$
(20)

where $\widetilde{\mathbf{R}}_{g}^{(w)} = \left(\widetilde{\mathbf{R}}_{g,1}^{(w)}, \dots, \widetilde{\mathbf{R}}_{g,N}^{(w)}\right)$, $\widetilde{\mathbf{R}}_{g,i}^{(w)} = (R_{g,i1}^{(w)}, \dots, R_{g,iT}^{(w)})^{\top}$ with $R_{g,it}^{(w)}$ being the *w*-th element of $\mathbf{R}_{g,it} = \mathbf{x}_{it} - \widehat{\mathbf{g}}_i(\tau_t)$, and $\mathbf{V}_{NT,2}$ is an $r \times r$ diagonal matrix with diagonal elements being the first *r* largest eigenvalues of the matrix $(NTp)^{-1} \sum_{w=1}^{p} \widetilde{\mathbf{R}}_{g}^{(w)} \widetilde{\mathbf{R}}_{g}^{(w)^{\top}}$.

Endogenous factor models

Corollary 3.2 (CLT, endogenous factor case) Let Assumptions 1.(i-v), 2-3, 6 hold. Suppose

$$\max\left\{\sqrt{\frac{N}{Th}},\sqrt{\frac{T}{N}}\right\}\kappa^{n-2}\to 0.$$

We have Theorem 2.3.(1-3) holds.

An example with exogenous factors

Example 1 Consider the following data generating process:

$$Y_{it} = X_{it,1}\beta_{1i}(\tau_t) + X_{it,2}\beta_{2i}(\tau_t) + \lambda_{i,1}F_{t,1} + \lambda_{i,2}F_{t,2} + \varepsilon_{it},$$

where

- $(\beta_{1i}(u), \beta_{2i}(u)) = (\sin(\pi u) + \cos(0.25\pi i), \cos(\pi u) + 0.5\sin(0.25\pi i));$
- $X_{it,1} = g_{i1}(\tau_t) + \gamma_{i1,1}G_{t,1} + \gamma_{i2,1}G_{t,2} + \eta_{it,1};$
- $X_{it,2} = g_{i2}(\tau_t) + \gamma_{i1,2}G_{t,1} + \gamma_{i2,2}G_{t,2} + \eta_{it,2};$
- $(g_{i1}(u), g_{i2}(u)) = (3\cos(\pi(u+0.25i)), 5\sin(\pi(u+0.25i));$
- $F_{t,1} = \rho_{F_1}F_{t-1,1} + v_{F_1,t}$ with $\rho_{F_1} = 0.6$;
- $F_{t,2} = \rho_{F_2}F_{t-1,2} + v_{F_2,t}$ with $\rho_{F_2} = 0.4$;
- $(G_{t,1}, G_{t,2}) \sim i.i.d.N(0, 1)$; the loadings and error terms: $\sigma_{ij,1} = 0.8^{|i-j|}$;

An example with exogenous factors

For $\widehat{\boldsymbol{\beta}}^{(n)}_w(\tau)$

- $w_i = \frac{1}{N}$, for i = 1, 2, ..., N;
- ► *h*_{cv}: leave-one-out cross-validation method;
- Epanechnikov kernel is adopted.

For $\widehat{\mathbf{F}}_{t}^{(n)}$ and $\widehat{\boldsymbol{\lambda}}_{i}^{(n)}$,

• r = 2 as given.

An example with exogenous factors

- Replication times: R = 1000 times;
- ► For each replication,

$$\mathrm{MSE}(\widehat{\beta}_{l,w}^{(n)}) = \frac{1}{T} \sum_{t=1}^{T} \left(\widehat{\beta}_{l,w}^{(n)}\left(\tau_{t}\right) - \beta_{l,w}\left(\tau_{t}\right) \right)^{2},$$

for l = 1, 2, where $\beta_{l,w}(\tau_t) = N^{-1} \sum_{i=1}^{N} \beta_{l,i}(\tau_t)$ are true values.

The second canonical correlation coefficients between {λ_i⁽ⁿ⁾} and {λ_i}, {F_t⁽ⁿ⁾} and F_t are computed respectively for each replication.

An example with exogenous factors

MSE	$\widehat{eta}_{w,1}^{(n)}$					$\hat{\beta}_{w,2}^{(n)}$					
N/T	10	20	40	80		10	20	40	80		
10	0.1771	0.0845	0.0454	0.0219		0.0531	0.0185	0.0077	0.0046		
	(0.1755)	(0.0343)	(0.0203)	(0.0119)		(0.0775)	(0.0135)	(0.0034)	(0.0023)		
20	0.1232	0.0650	0.0172	0.0123		0.0329	0.0133	0.0041	0.0026		
	(0.0959)	(0.0174)	(0.0079)	(0.0051)		(0.0285)	(0.0075)	(0.0017)	(0.0010)		
40	0.0954	0.0533	0.0154	0.0070		0.0225	0.0102	0.0036	0.0018		
	(0.0209)	(0.0123)	(0.0053)	(0.0027)		(0.0147)	(0.0038)	(0.0009)	(0.0005)		
80	0.0898	0.0455	0.0167	0.0046		0.0200	0.0083	0.0037	0.0015		
	(0.0159)	(0.0084)	(0.0039)	(0.0017)		(0.0128)	(0.0020)	(0.0006)	(0.0004)		

Table 1: Means and SDs of the mean squared errors for Example 4.1

An example with exogenous factors

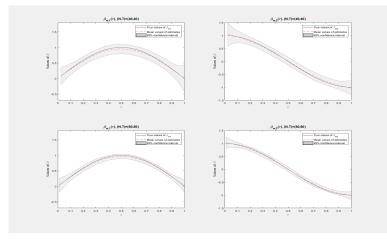


Figure 1: The simulated confidence intervals (Example 4.1)

An example with exogenous factors

SCC	$\widehat{\lambda}_{i}^{(n)}$					$\widehat{\mathbf{F}}_{t}^{(n)}$				
N/T	10	20	40	80		10	20	40	80	
10	0.3619	0.4877	0.5527	0.6042		0.4330	0.6693	0.8130	0.8736	
	(0.2266)	(0.2346)	(0.2349)	(0.2342)		(0.2447)	(0.2696)	(0.2218)	(0.1961)	
20	0.4461	0.6297	0.7433	0.8059		0.4455	0.7320	0.8914	0.9432	
	(0.2570)	(0.2388)	(0.1931)	(0.1521)		(0.2470)	(0.2337)	(0.1687)	(0.1260)	
40	0.5667	0.8081	0.8985	0.9213		0.5041	0.8374	0.9579	0.9818	
	(0.2688)	(0.1668)	(0.0597)	(0.0440)		(0.2410)	(0.1641)	(0.0446)	(0.0308)	
80	0.6934	0.9178	0.9514	0.9638		0.5573	0.9035	0.9718	0.9890	
	(0.2491)	(0.0565)	(0.0213)	(0.0125)		(0.2315)	(0.0612)	(0.0152)	(0.0058)	

Table 2: Means and SDs of the second canonical coefficients for Example 4.1

An example with endogenous factors

Example 2 Consider the following data generating process:

$$X_{it,1} = g_{i,1}(\tau_t) + \gamma_{i1,1}F_{t,1} + \gamma_{i2,1}F_{t,2} + \eta_{it,1}$$
$$X_{it,2} = g_{i,2}(\tau_t) + \gamma_{i1,2}F_{t,1} + \gamma_{i2,2}F_{t,2} + \eta_{it,2}$$
(21)

where $(g_{i1}(u), g_{i2}(u)) = (3\cos(\pi u), 5u)$. $(\gamma_{i1,1}, \gamma_{i1,2}), (F_{t,1}, F_{t,2})$ and $(\eta_{it,1}, \eta_{it,2})$ are following the same DGP in Example 1.

An example with endogenous factors

MSE	$\widehat{eta}_{w,1}^{(n)}$					$\widehat{\beta}_{w,2}^{(n)}$					
N/T	10	20	40	80		10	20	40	80		
10	0.2790	0.0883	0.0511	0.0181		0.0922	0.0213	0.0093	0.0051		
	(0.5040)	(0.0414)	(0.0278)	(0.0152)		(0.1979)	(0.0238)	(0.0056)	(0.0038)		
20	0.1514	0.0607	0.0192	0.0087		0.0599	0.0126	0.0047	0.0024		
	(0.1648)	(0.0257)	(0.0103)	(0.0060)		(0.1353)	(0.0067)	(0.0021)	(0.0014)		
40	0.1119	0.0537	0.0160	0.0045		0.0369	0.0107	0.0038	0.0015		
	(0.0783)	(0.0148)	(0.0061)	(0.0030)		(0.1087)	(0.0040)	(0.0011)	(0.0006)		
80	0.0906	0.0437	0.0128	0.0035		0.0250	0.0087	0.0032	0.0012		
	(0.0304)	(0.0100)	(0.0038)	(0.0016)		(0.0135)	(0.0023)	(0.0007)	(0.0004)		

Table 3: Means and SDs of the mean squared errors for Example 4.2

An example with endogenous factors

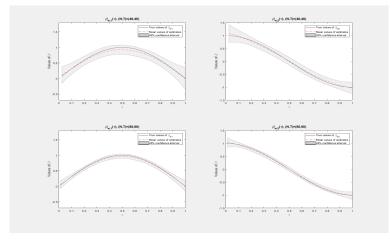


Figure 2: The simulated confidence intervals (Example 4.2)

An example with endogenous factors

SCC	$\widehat{\lambda}_{i}^{(n)}$					$\widehat{\mathbf{F}}_{t}^{(n)}$					
N/T	10	20	40	80		10	20	40	80		
10	0.4638	0.5178	0.5555	0.6054		0.3900	0.5814	0.7079	0.7652		
	(0.2444)	(0.2326)	(0.2291)	(0.2335)		(0.2511)	(0.2673)	(0.2442)	(0.2446)		
20	0.5328	0.6467	0.7218	0.7598		0.3888	0.6804	0.8091	0.8603		
	(0.2512)	(0.2188)	(0.1895)	(0.1788)		(0.2284)	(0.2247)	(0.2003)	(0.1724)		
40	0.6824	0.8007	0.8726	0.9032		0.4631	0.7906	0.9128	0.9510		
	(0.2029)	(0.1391)	(0.0804)	(0.0658)		(0.2217)	(0.1357)	(0.0716)	(0.0527)		
80	0.7202	0.8952	0.9426	0.9605		0.5079	0.8532	0.9475	0.9773		
	(0.2119)	(0.0901)	(0.0404)	(0.0146)		(0.1958)	(0.0941)	(0.0410)	(0.0112)		

Table 4: Means and SDs of the second canonical coefficients for Example 4.2

An empirical application in health economics Data description

The economic relationship between health care expenditure and income is reconsidered with the data set of OECD countries:

- The annual data is from 1971 to 2013 (T = 43) on 18 OECD countries (N = 18);
- ► *Y_{it}*: per capita health care expenditure (in US dollars, *HE_{it}*);
- ► *X*_{*it*,1}: per capita GDP (in US dollars, *GDP*_{*it*});
- $X_{it,2}$: the proportion of population above 15 years over all population (DR_{it}^{young}) ;
- ► X_{it,3}: the proportion of population above 65 years over all population (DR^{old}_{it});
- X_{it,4}: the proportion of government funding invested on health care industry in total health care expenditure (*GHE*_{it});
- all variables are expressed in natural logarithm.

Consider the following model:

$$HE_{it} = \beta_{1,it}GDP_{it} + \beta_{2,it}DR_{it}^{young} + \beta_{3,it}DR_{it}^{old} + \beta_{4,it}GHE_{it} + \sum_{m=1}^{r} \lambda_{mi}f_{mt} + \varepsilon_{it}, \quad (22)$$

where

- ► $(\beta_{1,i}(\tau), \beta_{2,i}(\tau), \beta_{3,i}(\tau), \beta_{4,i}(\tau))$: unknown deterministic functions;
- (f_{1t}, \ldots, f_{rt}) : common factors; $(\lambda_{1i}, \ldots, \lambda_{ri})$: loadings.

An empirical application in health economics The number of factors

The criterion proposed by Bai and Ng (2002):

$$IC(r) = \log\left(\frac{1}{NT}\sum_{i=1}^{N}\sum_{t=1}^{T}\hat{\varepsilon}_{it}^{2}\right) + r\left(\frac{N+T}{NT}\right)\log\left(\min\{N,T\}\right)$$
(23)

where $\hat{\varepsilon}_{it}$ is the estimated residuals from model (22) with *r* factors.

r	1	2	3	4	5	6	7	8
IC(r)	-6.6058	-6.5600	-6.5538	-6.4607	-6.4057	-6.3390	-6.2940	-6.2798

Table 5: The values of IC(r) in the determination of factor number

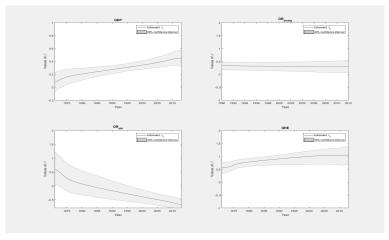


Figure 3: The estimated elasticities and confidence intervals



Different groups:

- The European countries: Austria, Denmark, Finland, Germany, Iceland, Ireland, Netherlands, Norway, Portugal, Spain, Sweden and the UK;
- Non-European countries: Australia, Canada, Japan, Korea, New Zealand and the US.

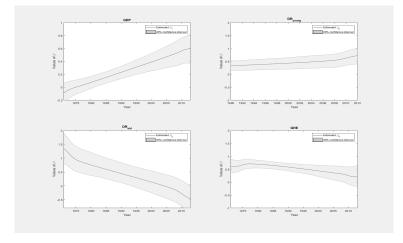


Figure 4: The estimated elasticities and confidence intervals (European OECD countries)



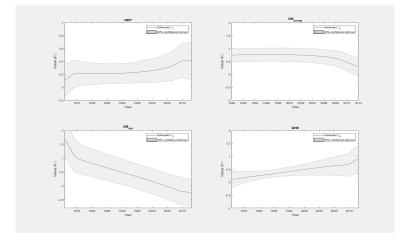


Figure 5: The estimated elasticities and confidence intervals (Non-European OECD countries)



Estimated loadings and factors

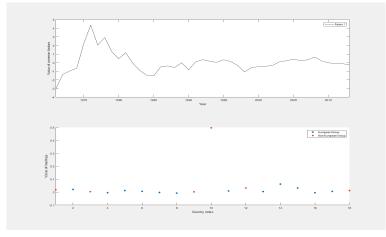


Figure 6: The estimated loadings and factors

Conclusions

Our contributions can be summarized as follows:

- ► Model:
 - Time-varying regression coefficients are introduced;
 - Heterogeneity is allowed.
- ► Method:
 - A recursive method is proposed to reduce the bias;
 - ► It can be generally used when the factors are exogenous or endogenous.
 - Asymptotic properties are established for the proposed estimators, including the factors and loadings.
- Empirical results: evidence of time-variation and heterogeneity in income elasticity of health care expenditure.

Thank You

Notation

Define

$$\mathbf{W}(\tau) = \operatorname{diag}\left(K(\frac{1-\tau T}{Th}), \dots, K(\frac{T-\tau T}{Th})\right)$$

$$\overline{\mathbf{M}}(\tau) = \begin{pmatrix} \overline{\mathbf{x}}_{1}^{\top} & \frac{1-\tau T}{Th} \overline{\mathbf{x}}_{1}^{\top} \\ \vdots & \vdots \\ \overline{\mathbf{x}}_{T}^{\top} & \frac{T-\tau T}{Th} \overline{\mathbf{x}}_{T}^{\top} \end{pmatrix}.$$
(24)

•
$$\widetilde{\mathbf{W}}(\tau) = \mathbf{W}(\tau) \otimes \mathbf{I}_N$$
,

$$\blacktriangleright \ \overline{\mathbf{y}} = (\overline{\mathbf{y}}_1^\top, \cdots, \overline{\mathbf{y}}_T^\top)^\top.$$

◀ Return

Notation

Define

$$\mathbf{y}_{t} = (y_{1t}, y_{2t}, \dots, y_{Nt})^{\top}, \quad \mathbf{x}_{t} = (\mathbf{x}_{1t}, \mathbf{x}_{2t}, \dots, \mathbf{x}_{Nt})$$
$$\mathbf{V} = (\mathbf{v}_{1}, \mathbf{v}_{2}, \dots, \mathbf{v}_{N})^{\top}, \quad \widetilde{\mathbf{F}}_{t} = \left(\widetilde{F}_{1t}, \widetilde{F}_{jt}, \dots, \widetilde{F}_{rt}\right)^{\top},$$
$$\widetilde{\mathbf{F}} = \left(\widetilde{\mathbf{F}}_{1}, \widetilde{\mathbf{F}}_{2}, \dots, \widetilde{\mathbf{F}}_{T}\right)^{\top}, \quad \boldsymbol{\varepsilon}_{t} = (\varepsilon_{1t}, \varepsilon_{2,t}, \dots, \varepsilon_{Nt})^{\top}.$$

Notation

Let
$$\mathbf{W}_0(\tau) = \text{diag}\left(K(\frac{1-\tau T}{Th}), \dots, K(\frac{T-\tau T}{Th})\right), \mathbf{W}(\tau) = \mathbf{W}_0(\tau) \otimes \mathbf{I}_N, \, \widetilde{\mathbf{y}}_t = \mathbf{M}_V \mathbf{y}_t,$$

 $\widetilde{\mathbf{x}}_t = \mathbf{x}_t \mathbf{M}_V \text{ and}$

$$\mathbf{M}(\tau) = \begin{pmatrix} \widetilde{\mathbf{x}}_1^\top & \frac{1-\tau T}{Th} \widetilde{\mathbf{x}}_1^\top \\ \vdots & \vdots \\ \widetilde{\mathbf{x}}_T^\top & \frac{T-\tau T}{Th} \widetilde{\mathbf{x}}_T^\top \end{pmatrix}.$$

Notation

Define

$$\mathbf{y}_i = (y_{i1}, \cdots, y_{iT})^{\top}, \quad \mathbf{W}(\tau) = \left(K\left(\frac{1-\tau T}{Th}\right), \cdots, K\left(\frac{T-\tau T}{Th}\right)\right)$$

and

$$\mathbf{M}_i = \begin{pmatrix} \mathbf{x}_{i1}^\top & \frac{1-\tau T}{Th} \mathbf{x}_{i1}^\top \\ \vdots & \\ \mathbf{x}_{iT}^\top & \frac{T-\tau T}{Th} \mathbf{x}_{iT}^\top \end{pmatrix}.$$

Notation

Notations:

•
$$\mathbf{\Omega}_3(t,s) = \mathbf{\Sigma}_{\lambda}^{-1}(h^{-1}K_{s,0}(\tau_t)\mathbf{\Omega}_1(t,s) + \mathbf{\Omega}_2(t,s)),$$

$$\blacktriangleright \ \lambda_i^{\dagger}(\tau_t) = \Sigma_{X,i}^{-1}(\tau_t) \left(\Sigma_{X,\lambda,i}(\tau_t) + E\left[\mathbf{x}_{it}\right] \lambda_i^{\top} \right),$$

•
$$\Delta_{F,i} = \Sigma_{v,F} \Omega_{F,i}^{-1} \Sigma_{v,F}^{\top}, \Sigma_{X,\lambda,i}(\tau_t) = E\left[\mathbf{x}_{it} \lambda_i^{\top}\right]$$

▶ Return

Assumptions

Assumption 1.

(i) α-mixing conditions on panel data are assumed as follows: {v_t, ε_t, F⁰_t} are strictly stationary and α-mixing across t; Let α_{ij}(|t - s|) represent the α-mixing coefficient between {ε_{it}} and {ε_{js}}. Assume that

$$\sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t=1}^{T} \left(\alpha_{ij}(t) \right)^{\delta/(4+\delta)} = O(N) \quad \text{and} \quad \sum_{i=1}^{N} \sum_{j=1}^{N} \left(\alpha_{ij}(0) \right)^{\delta/(4+\delta)} = O(N)$$

where $\delta > 0$ is chosen such that $E\left[\|\omega_{it}\|^{4+\delta}\right] < \infty$ with $\omega_{it} \in \{\lambda_t^0, F_t^0, \varepsilon_{it}, \mathbf{v}_{it}\}$. Let $\alpha(|t-s|)$ represent the α -mixing coefficient between $\{\mathbf{v}_{it}, F_t^0\}$ and $\{\mathbf{v}_{is}, F_s^0\}$. Assume that

$$\alpha(t) = O(t^{-\theta}),$$

where $\theta > (4 + \delta) / \delta$.

- (ii) $\{\varepsilon_{it}\}$ are identically distributed across *i* with zero mean and independent of $\{\mathbf{F}_{s}^{0}, \lambda_{j}^{0}, \mathbf{v}_{js}\}$, for any *i*, *j*, *t*, *s*.
- (iii) The unknown deterministic functions $\{\beta_i(\tau)\}$ have continuous derivatives of up to the second order on its support $\tau \in [0, 1]$, and the functions $\{g_i(\tau)\}$ are uniformly bounded: $\max_{1 \le i \le N} \sup_{\tau \in [0, 1]} ||\mathbf{g}_i(\tau)|| < \infty$.
- (iv) The kernel function $K(\cdot)$ is Lipschitz continuous with compact support on [-1, 1].
- (v) As $N, T \to \infty$, the bandwidth satisfies that $h \to 0$, max $\{N, T\}h^4 \to 0$ and min $\{N, T\}h^2 \to \infty$.
- (vi) Let $\mathbf{R}_{F}^{(n)} = \hat{\mathbf{F}}^{(n)} \mathbf{F}^{0}$. For the initial estimator $\hat{\mathbf{F}}^{(0)}$, suppose that $T^{-1/2} \|\mathbf{R}_{F}^{(0)}\| = O_{P} \left(\delta_{F,0}\right) \text{ and } (Th)^{-1/2} \|\mathbf{W}(\tau)^{\top} \mathbf{R}_{F}^{(0)}\| = O_{P} \left(\delta_{F,0}\right)$,

where $\delta_{F,0}$ satisfies that $NTh^4 \delta_{F,0}^2 \to 0$, $\delta_{F,0}^2/h \to 0$ and $\max\{N,T\}\delta_{F,0}^4/h \to 0$, as $N,T \to \infty$.

Return

Assumptions

Notation:

$$\begin{split} &\sigma_{v,\varepsilon,i}^{2} = \sigma_{\varepsilon}^{2} \boldsymbol{\Sigma}_{v,i} + 2\sum_{t=2}^{\infty} E\left[\varepsilon_{11}\varepsilon_{1t}\right] E\left[\mathbf{v}_{i1}\mathbf{v}_{it}^{\top}\right], \quad \sigma_{\varepsilon,0}^{2} = \sigma_{\varepsilon}^{2} + 2\sum_{t=2}^{\infty} E\left[\varepsilon_{11}\varepsilon_{1,t}\right], \quad \sigma_{\varepsilon}^{2} = E\left[\varepsilon_{11}^{2}\right], \\ &v_{0} = \int K(u)^{2} du, \quad \boldsymbol{\Sigma}_{\beta,i}^{0}(\tau) = v_{0}\left(\sigma_{v,\varepsilon,i}^{2} + \sigma_{\varepsilon,0}^{2} g_{i}(\tau) \mathbf{g}_{i}^{\top}(\tau)\right), \\ &\xi_{1,it} = \lambda_{i}^{0\top} \mathbf{F}_{t}^{0}, \quad \boldsymbol{\xi}_{2,it} = \mathbf{v}_{it} \lambda_{i}^{0\top}, \quad \sigma_{F,\varepsilon,0}^{2} = \sigma_{\varepsilon}^{2} \boldsymbol{\Sigma}_{F} + 2\sum_{t=2}^{\infty} E\left[\varepsilon_{11}\varepsilon_{it}\right] E\left[\mathbf{F}_{1}^{0} \mathbf{F}_{t}^{0\top}\right], \\ &\boldsymbol{\Sigma}_{\lambda,i}^{0} = \sigma_{F,\varepsilon,0}^{2} - \int_{0}^{1} \boldsymbol{\Sigma}_{v,F,i}^{\top} \boldsymbol{\Sigma}_{\lambda,i}^{-1}(v) \left(\sigma_{v,\varepsilon,i}^{2} + \sigma_{\varepsilon,0}^{2} \mathbf{g}_{i}(v) \mathbf{g}_{i}^{\top}(v)\right) \boldsymbol{\Sigma}_{\lambda,i}^{-1}(v) \boldsymbol{\Sigma}_{v,F,i} dv \end{split}$$

Assumption 2.

(i) Assume the following moment conditions on $\{\varepsilon_{it}, \xi_{1,it}, \xi_{2,it}\}$:

$$\begin{split} & \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t_{1}=1}^{T} \sum_{t_{2}=1}^{T} \sum_{t_{2}=1}^{T} \sum_{t_{3}=1}^{T} \sum_{t_{4}=1}^{T} |Cov(\varepsilon_{it_{1}}\varepsilon_{it_{2}}, \varepsilon_{jt_{3}}\varepsilon_{jt_{4}})| & \leq \quad CNT^{2} \\ & \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t_{1}=1}^{T} \sum_{t_{2}=1}^{T} \sum_{t_{3}=1}^{T} \sum_{t_{4}=1}^{T} |Cov(\xi_{1,it_{1}}\xi_{1,it_{2}}, \xi_{1,jt_{3}}\xi_{1,jt_{4}})| & \leq \quad CNT^{2} \\ & \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{t_{1}=1}^{T} \sum_{t_{2}=1}^{T} \sum_{t_{3}=1}^{T} \sum_{t_{4}=1}^{T} |Cov(\xi_{2,it_{1}}\xi_{2,it_{2}}^{\top}, \xi_{2,jt_{3}}\xi_{2,jt_{4}}^{\top})|| & \leq \quad CNT^{2} \end{split}$$

Appendix

Assumptions

Assumption 2.

(ii) Assume that $\Sigma_{v,i}$, Σ_F , $\Sigma_{\beta,i}^0(\tau)$ and $\Sigma_{\lambda,i}^0$ are positive definite and σ_{ε}^2 is a positive scalar.

(iii) Suppose that
$$\left\| N^{-1} \sum_{i=1}^{N} \lambda_i^0 \lambda_i^{0^{\top}} - \Sigma_{\lambda} \right\| = O_P \left(N^{-1/2} \right)$$
 and
 $N^{-1/2} \sum_{i=1}^{N} \lambda_i^0 \varepsilon_{it} \xrightarrow{D} \mathcal{N}(0, \Sigma_{F,t}^0),$

for any fixed *t*, where both Σ_{λ} , $\Sigma_{F,t}^{0}$ are positive definite.

(iv) Let h satisfy $\limsup_{N,T\to\infty} NTh^5 < \infty$, $NT^{-(4+\delta^*)/4} \to 0$, $N^{\delta^{\dagger}}T^{-\theta}h^{-3-\theta}(\log T)^{1+2\theta} \to 0$, for $0 < \delta^* < \delta$ and $\delta^{\dagger} = (6+\delta)/(4+\delta) - 2(1+\theta)/(2+\delta)$, where θ and δ are defined in Assumption 1.

Return

Appendix

Assumptions

Assumption 3. Let $E\left[\lambda_i^0 \lambda_i^{0\top} | \mathbf{v}_{i1}, \dots, \mathbf{v}_{iT}, \mathbf{F}_1^{0\top}, \dots, \mathbf{F}_T^{0\top}\right] = \boldsymbol{\Sigma}_{\lambda}$ almost surely, where $\boldsymbol{\Sigma}_{\lambda} = \lim_{N \to \infty} N^{-1} \sum_{i=1}^N \lambda_i^0 \lambda_i^{0\top}$ is positive definite. \blacktriangleleft Return

Assumptions for the heterogeneous model

Assumption 4.

(i) Assume that $E\left[\mathbf{v}_{it}\boldsymbol{\lambda}_{i}^{0\top}\right] = E\left[\mathbf{v}_{it}\mathbf{F}_{t}^{0\top}\right] = \mathbf{0}_{p\times r}$ and $E[\lambda_{i}] = \mathbf{0}_{r}$.

(ii) Define that

$$\begin{split} \widetilde{\sigma}_{v,\varepsilon}^{2}(i,j,\tau) &= \mathbf{\Sigma}_{X,i}^{-1}(\tau)\sigma_{v,\varepsilon}^{2}(i,j)\mathbf{\Sigma}_{X,j}^{-1}(\tau), \\ \widetilde{\sigma}_{\varepsilon}^{2}(i,j,\tau) &= \sigma_{\varepsilon}^{2}(i,j)\mathbf{\Sigma}_{X,i}^{-1}(\tau)\mathbf{g}_{i}(\tau)\mathbf{g}_{j}^{\top}(\tau)\mathbf{\Sigma}_{X,j}^{-1}(\tau), \\ \mathbf{\Sigma}_{\beta,w}(\tau) &= \lim_{N \to \infty} \gamma_{N,w} v_{0} \sum_{i=1}^{N} \sum_{j=1}^{N} w_{N,i} w_{N,j} \left(\widetilde{\sigma}_{\varepsilon}^{2}(i,j,\tau) + \widetilde{\sigma}_{v,\varepsilon}^{2}(i,j,\tau)\right). \end{split}$$

We assume $\Omega_{F,i}$ and $\Sigma_{\beta,w}(\tau)$ are positive-definite matrices, where $\Omega_{F,i}$ is defined in Theorem 1.

(iii) The bandwidth *h* satisfies that: $\lim_{N\to\infty} \gamma_{N,w} h^3 = 0$.

◀ Return

Assumptions

Assumption 5.

(i) Assume the estimators $\widehat{F}^{(0)}$ and $\widehat{\Lambda}^{(0)}$ satisfy the following identification condition:

$$N^{-1}\widehat{\mathbf{\Lambda}}^{(0)\top}\widehat{\mathbf{\Lambda}}^{(0)} = \text{diagnal} \text{ and } T^{-1}\widehat{\mathbf{F}}^{(0)\top}\widehat{\mathbf{F}}^{(0)} = \mathbf{I}_r.$$

- (ii) Assume the true values F^0 and Λ^0 satisfy the identification conditions in Assumption 5.1.
- (iii) Suppose \mathbf{F}_t^0 is conditionally uncorrelated with $\mathbf{\Lambda}^0$, \mathbf{v}_1 , ..., \mathbf{v}_T :

$$E\left[\mathbf{F}_{t}^{0}|\mathbf{\Lambda}^{0},\mathbf{v}_{1},\ldots,\mathbf{v}_{T}\right]=0_{r}.$$

In addition, we assume $\{\mathbf{F}_t^0| \mathbf{\Lambda}^0, \mathbf{v}_1, \dots, \mathbf{v}_T\}$ satisfies the α -mixing condition in Assumption 1.

(iv) Suppose the following moment conditions can hold:

$$\begin{split} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3=1}^{T} \sum_{t_4=1}^{T} \left\| E \left[\mathbf{F}_{t_1}^{0} \mathbf{F}_{t_2}^{0\top} \mathbf{F}_{t_3}^{0} \mathbf{F}_{t_4}^{0\top} \right] \right\| &\leq CT^2, \\ \sum_{i=1}^{N} \sum_{j=1}^{T} \sum_{t_1=1}^{T} \sum_{t_2=1}^{T} \sum_{t_3 \neq t_1}^{T} \sum_{t_4 \neq t_2}^{T} \left| E \left[\varepsilon_{it_1} \varepsilon_{jt_2} \varepsilon_{it_3} \varepsilon_{jt_4} \right] \right| &\leq CNT^2. \end{split}$$



Assumptions

Assumption 6.

(i) Assume the estimators $\hat{\mathbf{F}}^{(0)}$ and $\hat{\gamma}_i^{(0)}$ satisfy the following identification condition:

$$N^{-1}\sum_{i=1}^{N}\widehat{\gamma}_{i}^{(w,0)\top}\widehat{\gamma}_{i}^{(w,0)} = \text{diagnal} \quad \text{and} \quad T^{-1}\widehat{\mathbf{F}}^{(0)\top}\widehat{\mathbf{F}}^{(0)} = \mathbf{I}_{r},$$

for $w = 1, 2, \dots, p$, where $\widehat{\gamma}_i^{(w,0)}$ is the *w*-th column of $\widehat{\gamma}_i^{(0)\top}$.

- (ii) Assume the true values \mathbf{F}^0 and λ^0 satisfy the identification conditions in Assumption 5.1.
- (iii) The unknown deterministic function g_i(τ) has continuous derivatives of up to the second order on its support τ ∈ [0, 1]. Assume that the loadings {γ_i} are deterministic and uniformly bounded.
- (iv) Suppose we have the following moment conditions:

$$\begin{split} \sum_{t_1=1}^T \sum_{t_2=1}^T \sum_{t_3=1}^T \sum_{t_4=1}^T \left\| E \left[\mathbf{F}_{t_1}^0 \mathbf{F}_{t_2}^0 \mathbf{F}_{t_3}^0 \mathbf{F}_{t_4}^{0\top} \right] \right\| &\leq CT^2, \\ \sum_{i=1}^N \sum_{j=1}^N \sum_{t_1=1}^T \sum_{t_2=1}^T \sum_{t_3\neq t_1}^T \sum_{t_4\neq t_2}^T \left\| E \left[\boldsymbol{\eta}_{it_1} \boldsymbol{\eta}_{jt_2}^\top \boldsymbol{\eta}_{it_3} \boldsymbol{\eta}_{jt_4}^\top \right] \right\| &\leq CNT^2. \end{split}$$

Estimated loadings and factors

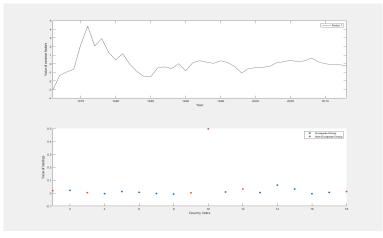


Figure 7: The estimated loadings and factors

Bootstrapping

The details for our bootstrapping method are as follows:

- Step 1. Calculate the residuals $\{\overline{\epsilon}_{it}\}$ for the estimation method discussed in Section 2.
- Step 2. Resample the residuals and obtain $\{\bar{\varepsilon}_{it}^*\}$, where $\varepsilon_{it}^* = \bar{\varepsilon}_k$ and k is randomly selected from $\{1, \ldots, T\}$. Then the bootstrapping sample $\{Y_{it}^*\}$ can be generated with $\{\bar{\varepsilon}_{it}^*\}$.
- Step 3. The bootstrapping estimator $\overline{\beta}_t^*$ can be obtained using the data set $\{Y_{it}^*\}$.
- Step 4. Repeat Steps 2 and 3 1000 times to obtain the 90% confidence intervals.



Discussions on initial estimator: exogenous factors

PCA method to find $\widehat{\mathbf{F}}^{(0)}$:

(1) First, ignore the common factor part and estimate β_{it} using local linear method:

$$\widehat{\boldsymbol{\beta}}_{i}^{(0)}(\tau) = \begin{bmatrix} \mathbf{I}_{p}, \mathbf{0}_{p} \end{bmatrix} \left(\mathbf{M}_{i}^{\top}(\tau) \mathbf{W}(\tau) \mathbf{M}_{i}(\tau) \right)^{-1} \mathbf{M}_{i}^{\top}(\tau) \mathbf{W}(\tau) \mathbf{y}_{i},$$

for i = 1, ..., N.

(2) Then estimate F using the PCA method as follows:

$$\frac{1}{NT}\sum_{i=1}^{N} \mathbf{R}_{3,i} \mathbf{R}_{3,i}^{\top} \widehat{\mathbf{F}}^{(0)} = \widehat{\mathbf{F}}^{(0)} \mathbf{V}_{NT,F},$$
(25)

where
$$\mathbf{R}_{3,i} = \left(R_{i1}(\widehat{\boldsymbol{\beta}}_{1}^{(0)}(\tau_{1})), \dots, R_{iT}(\widehat{\boldsymbol{\beta}}_{i}^{(0)}(\tau_{T}))\right)^{\top}$$
 and $R_{it}(\boldsymbol{\beta}) = y_{it} - \mathbf{x}_{it}^{\top}\boldsymbol{\beta}(\tau_{t}).$

Discussions on initial estimator: exogenous factors

Corollary 3.2 Under some regularity conditions and $\widehat{\mathbf{F}}^{(0)}$ satisfies (25),

$$\frac{1}{\sqrt{T}} \left\| \widehat{\mathbf{F}}^{(0)} - \mathbf{F} \mathbf{H}_1 \right\| = O_p \left(\max\{ (Th)^{-1/2}, N^{-1/2}, h^2 \} \right), \tag{26}$$

where $\mathbf{H}_1 = (NT)^{-1} \sum_{i=1}^N \lambda_i \lambda_i^\top \mathbf{F}^\top \widehat{\mathbf{F}}^{(0)} \mathbf{V}_{NT,1}^{-1}$.

▶ See Assumptions

Discussions on initial estimator: endogenous factors

Consider the following model:

$$y_{it} = \mathbf{x}_{it}^{\top} \boldsymbol{\beta}_{it} + \boldsymbol{\lambda}_{i}^{\top} \mathbf{F}_{t} + \varepsilon_{it}$$
$$\mathbf{x}_{it} = \mathbf{g}_{i}(\tau_{t}) + \boldsymbol{\gamma}_{i}^{\top} \mathbf{F}_{t} + \boldsymbol{\eta}_{it}$$

PCA method to estimate $\widehat{\mathbf{F}}^{(0)}$,

(1) We first estimate the $\mathbf{g}_i(\tau)$ using local linear method:

$$\widehat{\mathbf{g}}_{i}^{(w)}(\tau) = [1,0] \left(\mathbf{M}_{T}^{\top}(\tau) \mathbf{W}(\tau) \mathbf{M}_{T}(\tau) \right)^{-1} \mathbf{M}_{T}^{\top}(\tau) \mathbf{W}(\tau) \widetilde{\mathbf{x}}_{i}^{(w)}$$
(27)

where $\hat{g}_i^{(w)}(\tau)$ is the *w*-th element of $\hat{\mathbf{g}}_i(\tau)$, $\tilde{\mathbf{x}}_i^{(w)} = \left(x_{i1}^{(w)}, \cdots, x_{iT}^{(w)}\right)^\top$ and $x_{it}^{(w)}$ is the *w*-th element of \mathbf{x}_{it} .

(2) Then \mathbf{F}_t can be estimated by the PCA method:

$$\left(\frac{1}{NTp}\sum_{w=1}^{p}\widetilde{\mathbf{R}}_{g}^{(w)}\widetilde{\mathbf{R}}_{g}^{(w)\top}\right)\widehat{\mathbf{F}}^{(0)} = \widehat{\mathbf{F}}^{(0)}\mathbf{V}_{NT,g}$$
(28)

where $\widetilde{\mathbf{R}}_{g}^{(w)} = \left(\widetilde{\mathbf{R}}_{g,1}^{(w)}, \dots, \widetilde{\mathbf{R}}_{g,N}^{(w)}\right), \widetilde{\mathbf{R}}_{g,i}^{(w)} = (R_{g,i1}^{(w)}, \dots, R_{g,iT}^{(w)})^{\top}$ and $R_{g,it}^{(w)}$ is the *w*-th element of $\mathbf{R}_{g,it} = \mathbf{x}_{it} - \widehat{\mathbf{g}}_i(\tau_t)$.

Discussions on initial estimator: endogenous factors

Corollary 3.3 Under some regularity conditions and $\widehat{\mathbf{F}}^{(0)}$ satisfies (28),

$$\frac{1}{\sqrt{T}} \left\| \widehat{\mathbf{F}}^{(0)} - \mathbf{F} \mathbf{H}_1 \right\| = O_p \left(\max\{ (Th)^{-1/2}, N^{-1/2}, h^2 \} \right),$$
(29)
where $\mathbf{H}_2 = \frac{1}{NTp} \sum_{w=1}^p \sum_{i=1}^N \gamma_i^{(w)} \gamma_i^{(w)\top} \mathbf{F}^\top \widehat{\mathbf{F}}^{(0)} \mathbf{V}_{NT,2}^{-1}.$
 \diamond See Assumptions \diamond Return to Estimation

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